

# **SKEE 2073**

# **Signals & Systems**

**Chapter 5 (Part I):  
Frequency Response and Filter**

# Outline

**Introduction**

**Transfer Function**

**Frequency Response Plot**

**Bode Plot**

**Real Poles and Zeros**

# Introduction

- ❖ The frequency response of a circuit describes the relationships between the amplitudes and phase angles of the input and output sinusoids which are frequency dependant.
- ❖ Bode plots is a generalizations of obtaining the frequency response of a network based on the transfer functions.
- ❖ Bode plots allow us to approximate the frequency response of a circuit using straight line approximations and becomes the industry standard method of presenting frequency response information.

# Application

- ❑ Most networks behave or act as filters.
- ❑ Many applications need to retain components in a given range of frequencies and discard the components in another range.
- ❑ This can be accomplished by the use of electrical networks called filters.

# Transfer Function

- Defined as the ratio of the phasor output voltage to the phasor input voltage as a function of frequency.

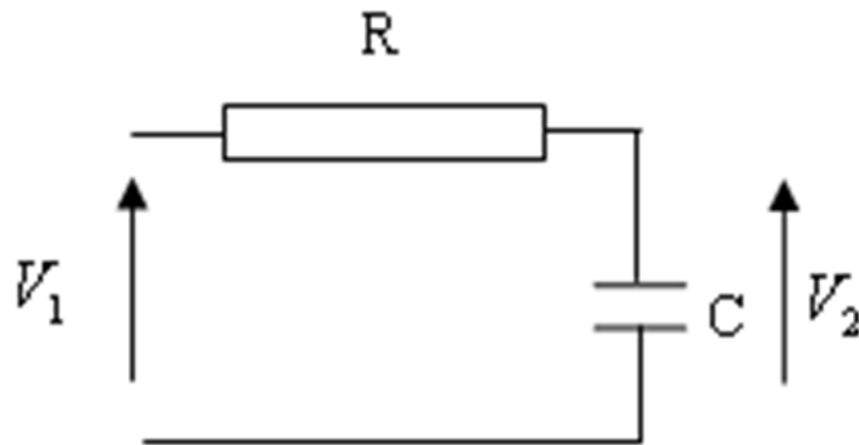
$$H(s) = \frac{V_{out}}{V_{in}}$$

- Magnitude of transfer function shows how the amplitude of each frequency component is affected by the network.
- Phase of transfer function shows how the phase of each frequency component is affected by the network.

# Example 1

Find the transfer function of the network below given

$$\text{as } H(s) = \frac{V_2}{V_1}$$



# Example 1: Solution

- ❖ The transfer function is found by voltage division

$$H(s) = \frac{1/sC}{R + 1/sC} = \frac{1}{sRC + 1}$$

where  $s = \sigma + j\omega$  . At steady state  $\sigma = 0$  ,  $s = j\omega$  .

Therefore the magnitude and angle of H(s) are

$$|H(j\omega)| = \frac{1}{\sqrt{1 + (\omega RC)^2}} \quad \theta(\omega) = -\tan^{-1}(\omega RC)$$

## Example 2

- Given the transfer function of a network as

$$H(s) = \frac{s10^4}{s^2 + 2000s + 5 \times 10^6}$$

- Evaluate the transfer function at  $\omega = 1000$  rad/s and  $\omega = 3000$  rad/s.



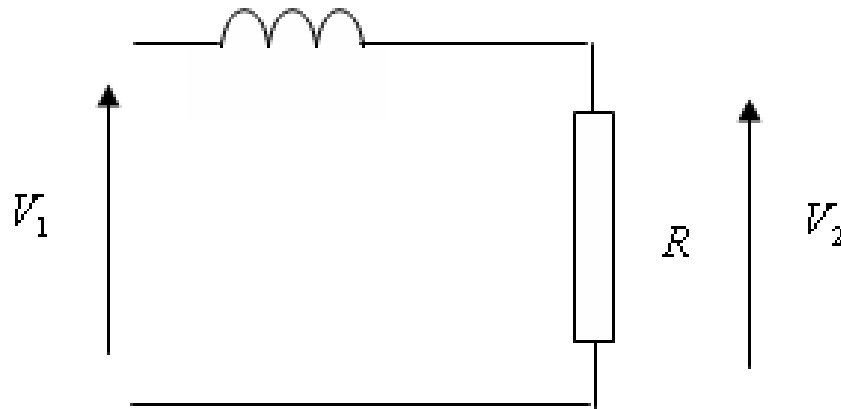
## Example 2: Solution

❑ At  $\omega = 1000$  rad/s, the value of  $H(s)$  is:

$$\begin{aligned}
 H(j1000) &= \frac{(j1000)10^4}{(j1000)^2 + 2000(j1000) + 5 \times 10^6} \\
 &= \frac{j10^7}{(5 \times 10^6 - 10^6) + j2 \times 10^6} = \frac{j10}{4 + j2} \\
 &= \frac{10e^{j90^\circ}}{\sqrt{20}e^{j26.6^\circ}} = 2.24e^{j63.4^\circ}
 \end{aligned}$$

## Example 3

- ❖ Find the frequency response of the system shown below at frequency  $\omega_1 = 1000 \pi$ ,  $\omega_2 = 3000 \pi$ ,  $\omega_3 = 5000 \pi$ , and  $\omega_4 = 7000 \pi$ . Given the value of  $R = 200 \pi \Omega$  and  $L = 0.1 \text{ H}$ .



## Example 3: Solution

- ❖ To find the frequency response of the system for each frequency, we need to evaluate the transfer function.

$$H(s) = \frac{V_2}{V_1} = \frac{R}{R + sL}$$

- ❖ For  $s = j\omega$

$$H(j\omega) = \frac{R}{R + j\omega L} = \frac{1}{1 + j(\omega L/R)}$$

## Example 3: Solution (cont.)

- The algebraic expression for the transfer function may be simplified in form by defining  $\omega_p = R/L = 2000 \pi$ .  $\omega_p$  is sometimes referred as “corner frequency”. Then:

$$H(j\omega) = \frac{\angle -\tan^{-1}(\omega / \omega_p)}{\sqrt{1 + (\omega / \omega_p)^2}} = |H(j\omega)| \angle \theta(\omega)$$

- At  $\omega_1, \omega_2, \omega_3, \omega_4$ :

$$H(j1000\pi) = \frac{\angle -\tan^{-1} 0.5}{(1+0.25)^{1/2}} = 0.89 \angle -26.6$$

$$H(j3000\pi) = \frac{\angle -\tan^{-1} 1.5}{(1+2.25)^{1/2}} = 0.55 \angle -56.3$$

$$H(j5000\pi) = \frac{\angle -\tan^{-1} 2.5}{(1+6.25)^{1/2}} = 0.37 \angle -68.2$$

$$H(j7000\pi) = \frac{\angle -\tan^{-1} 3.5}{(1+12.25)^{1/2}} = 0.27 \angle -74.1$$

# FREQUENCY RESPONSE

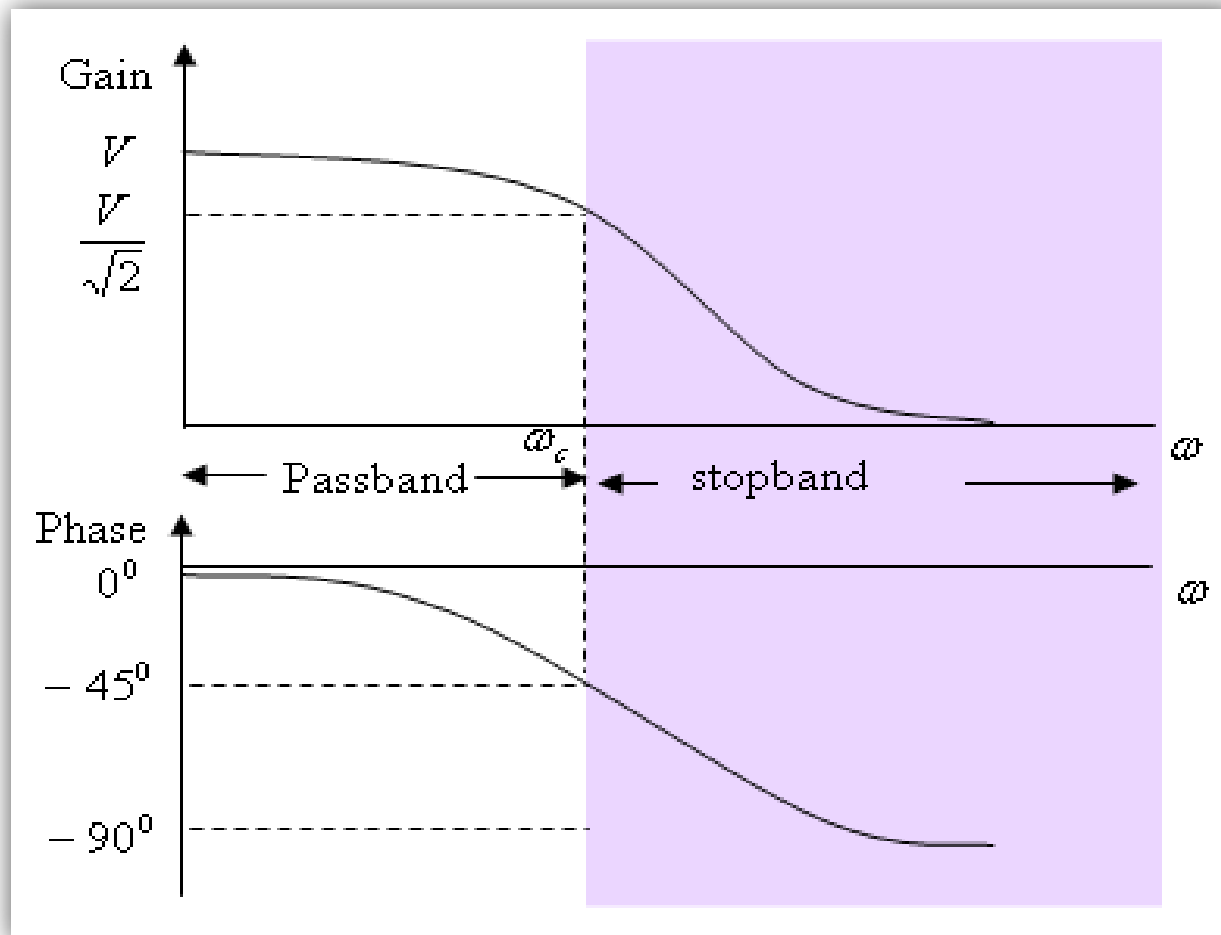
- ✿ Frequency response describes the output amplitude and the output phase of the network.
- ✿ Generally it is in a form of a filter function.

Output amplitude =  $|H(j\omega)|$  x input amplitude **(GAIN)**

Output phase = input phase +  $\theta(\omega)$  **(PHASE)**

# Frequency Response Plot

- Frequency response: Gain and phase response.



# Filter

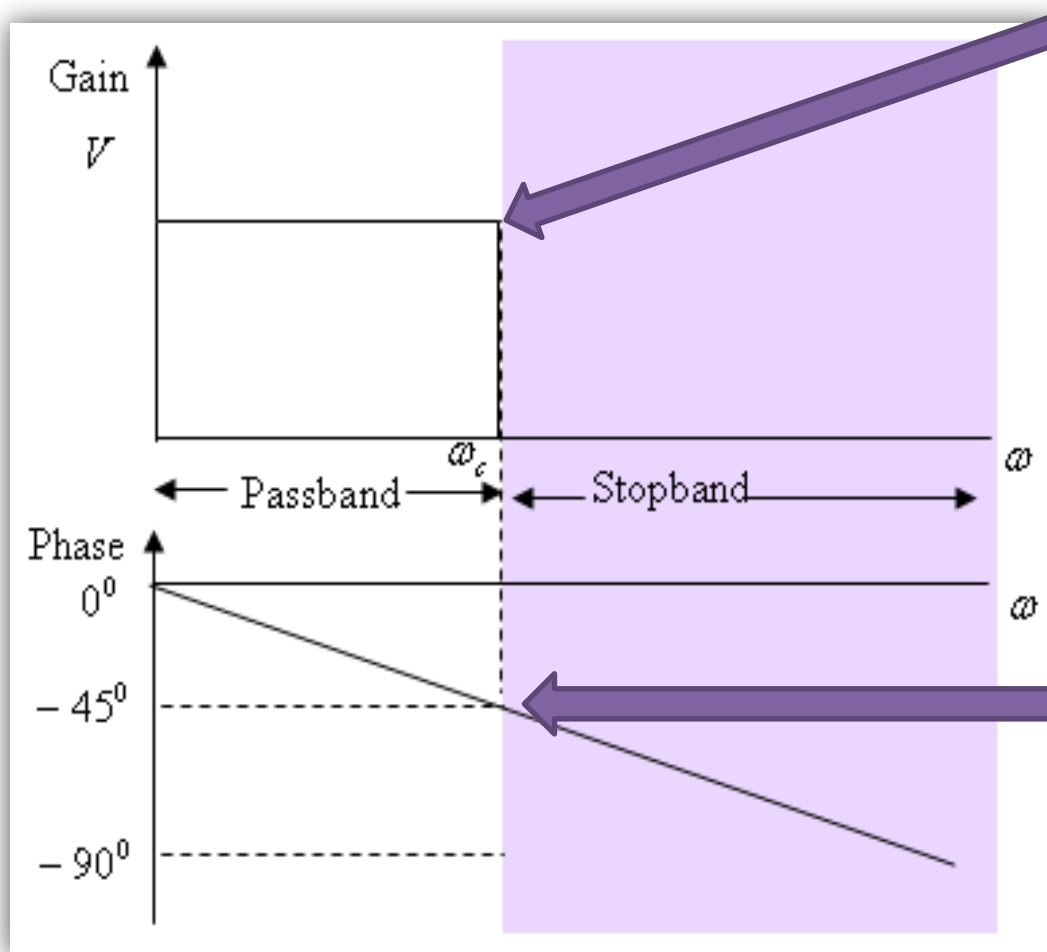
- Special network purposely designed to block unwanted frequencies.
- **Passive filter network** consists of passive elements such as  $L$ ,  $C$ , and  $R$ .
- **Active filter network** consists of active element such as op-amp and transistors.

## Filter (cont.)

- The frequency range over which the output is significantly attenuated is called *stopband*.
- The frequency range over which there is little attenuation is called *passband*.
- The *cutoff frequency*,  $\omega_c$  is defined as the boundary between passband and stopband.



# Ideal Filter

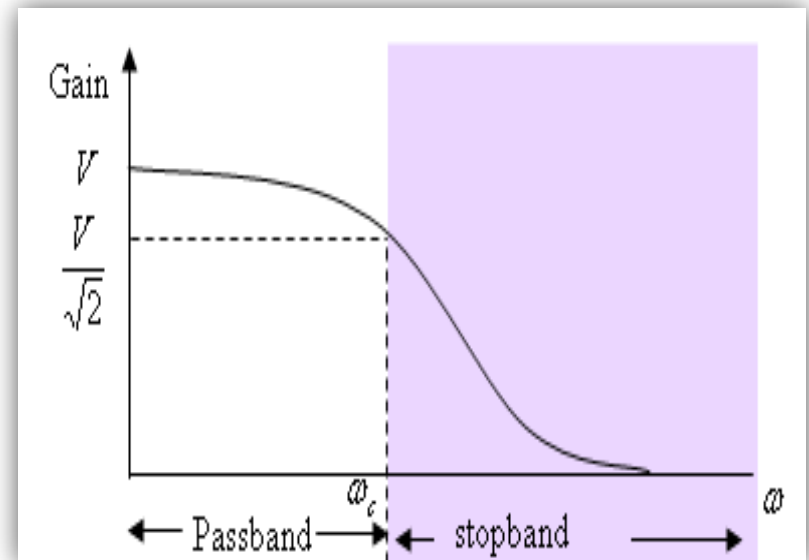


- Sharp cutoff frequency.

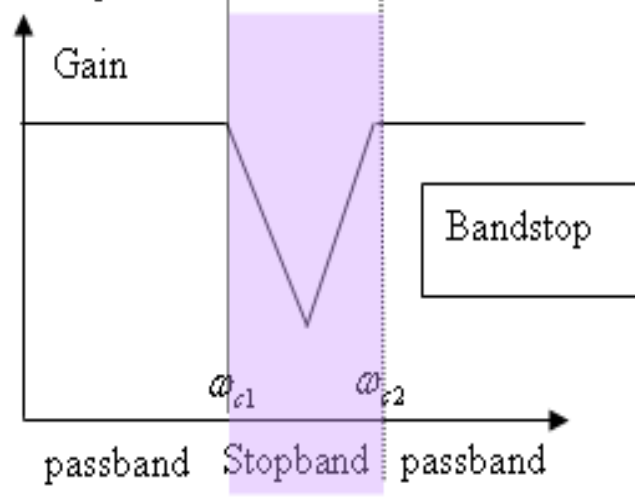
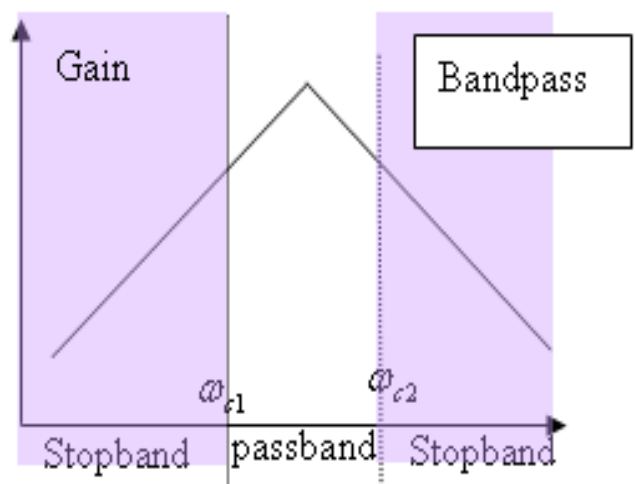
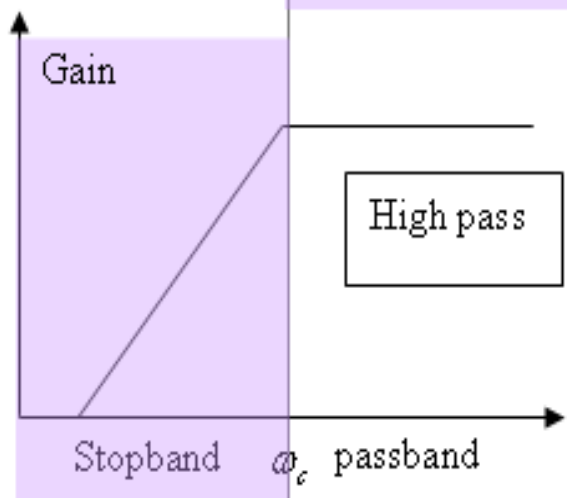
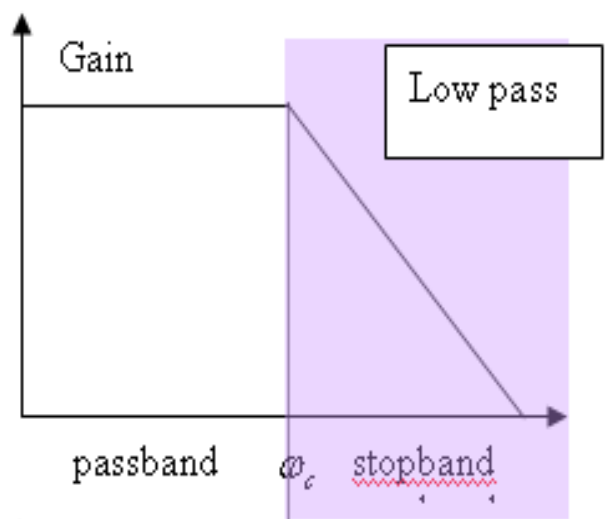
- Linear phase change.

# Practical Filter

- ❑ The transition from passband to stopband is gradual.
- ❑ The *cutoff frequency* is at which the gain has decreased by a factor of *0.707 from its maximum* value passband gain.
- ❑ In terms of power, the cutoff frequency is at half the maximum power of -3dB point.



# Types of Filter



# Bandwidth of the Filter

- The bandwidth of a filter is defined as the range spanned by its passband.
- E.g. for bandpass filter, the bandwidth is the difference in the two cutoff frequencies:

$$BW = \omega_{c2} - \omega_{c1}$$

