

# SKAA 1213 - Engineering Mechanics

TOPIC 2

## RESULTANT AND RESOLUTION OF FORCES

Lecturers:

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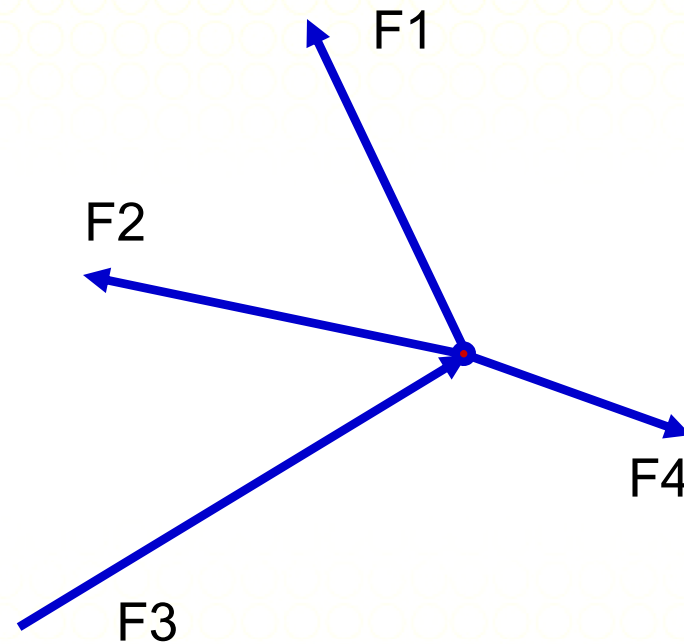
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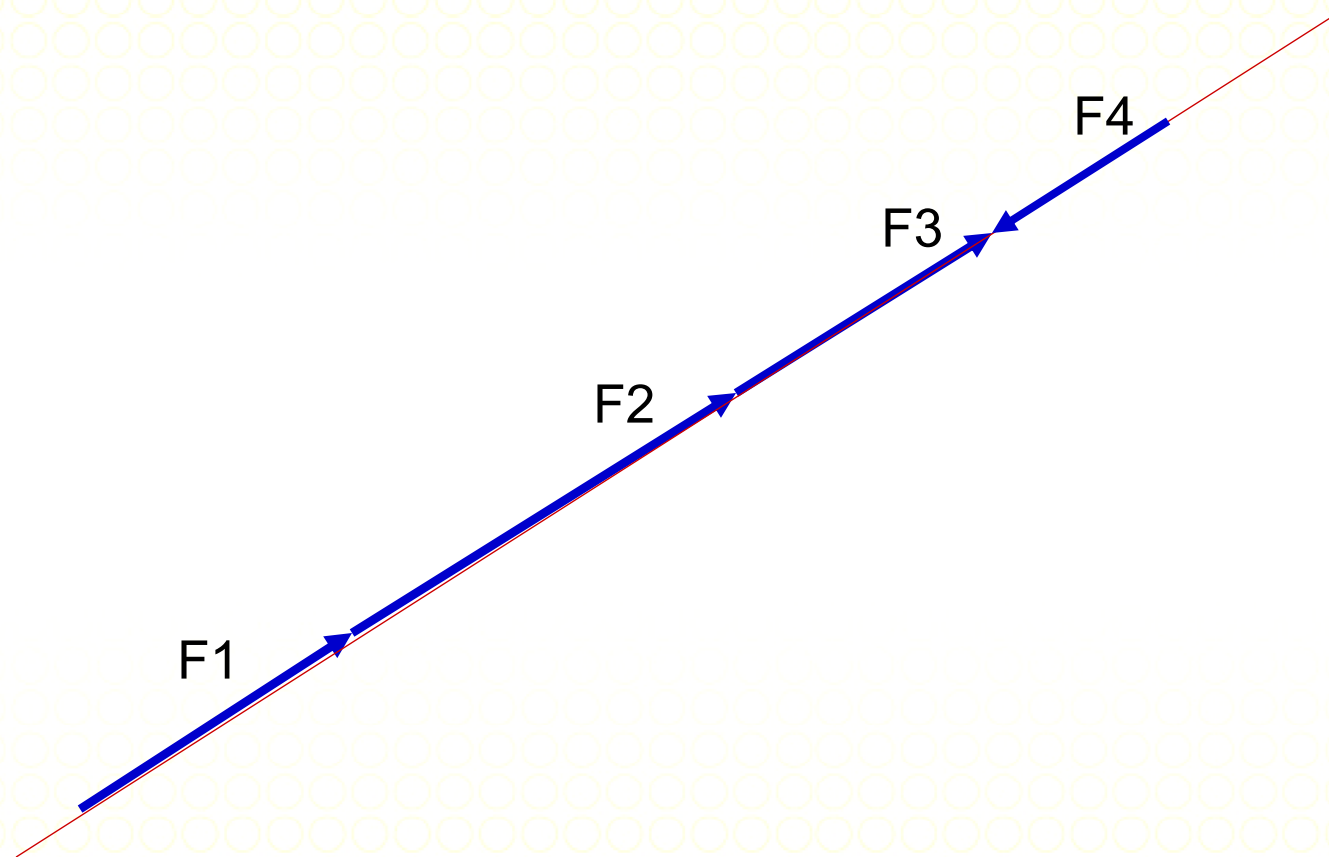
# Concurrent Forces –

forces acting at a point

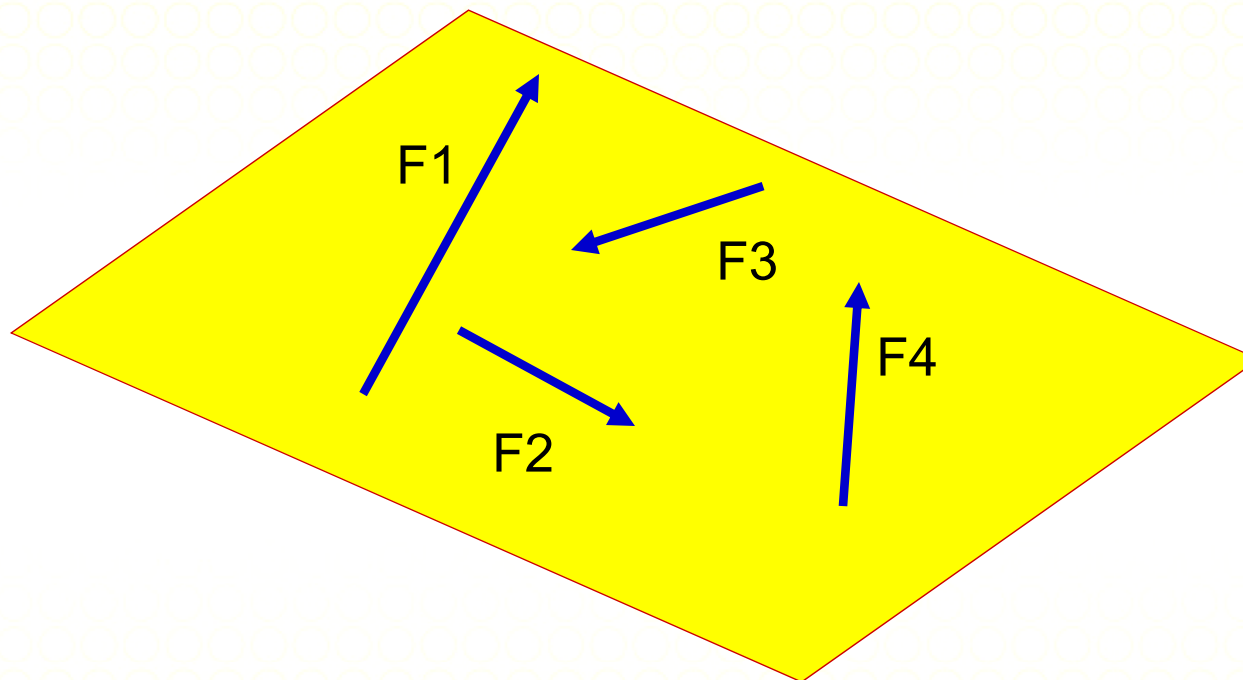


# Collinear Forces –

forces acting in the same line



# Coplanar Forces – forces acting in a same plane





Force is a vector, therefore parallelogram law is applicable.

### Used to;

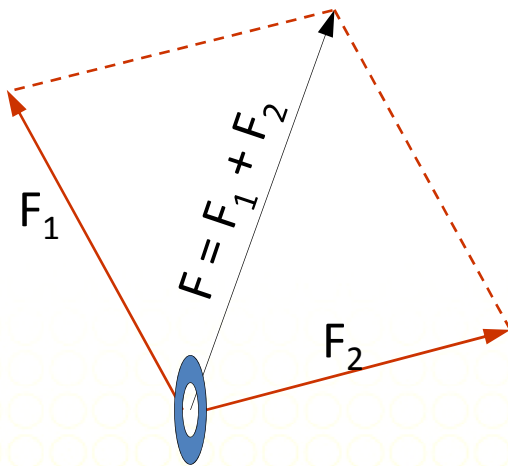
- 1) To find **resultant** force.
- 2) Resolving a known force into two **components**.

# Vector Addition of Forces

If only **two** forces are added, the resultant the **forces** acting at a point can be determined by;

*Parallelogram law*

*Apply the sine and cosine laws.*

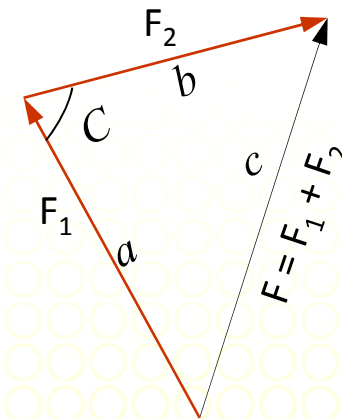


Sine Law:

$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

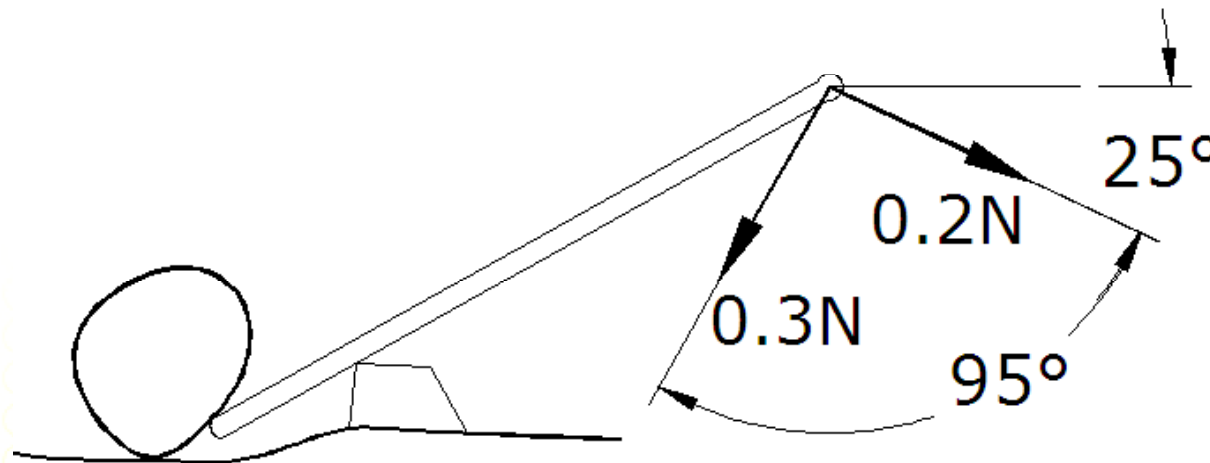
Cosine Law:

$$c^2 = a^2 + b^2 - 2ab \cos C$$



# Example 1

Determine the magnitude of the resultant force on the lever shown and its direction measured counterclockwise from the positive x axis. *[Answer:  $R = 0.346\text{ N}$ ,  $\beta = 275.3^\circ$ ]*



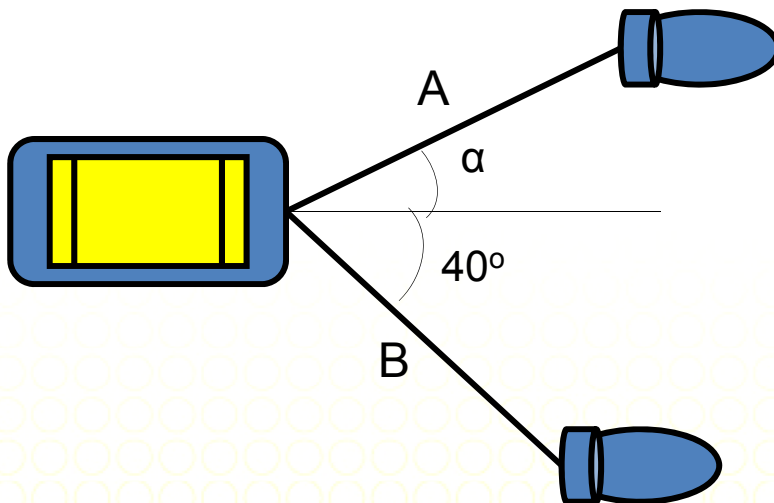
# Example 2

A barge is pulled by two tugboats. If the resultant of the forces exerted by the tugboats is 30 kN directed along the axis of the barge,;

- determine the tension in each of the ropes when  $\alpha = 35^\circ$ ,
- determine  $\alpha$  for which the tension in rope A is minimum.

$$(a) T_A = 20 \text{ kN}, T_B = 17.8 \text{ kN}$$

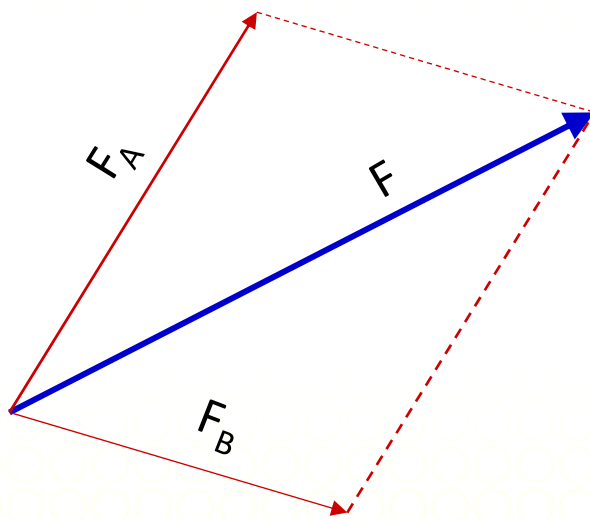
$$(b) T_A = 19.3 \text{ kN}, T_B = 23.0 \text{ kN}$$



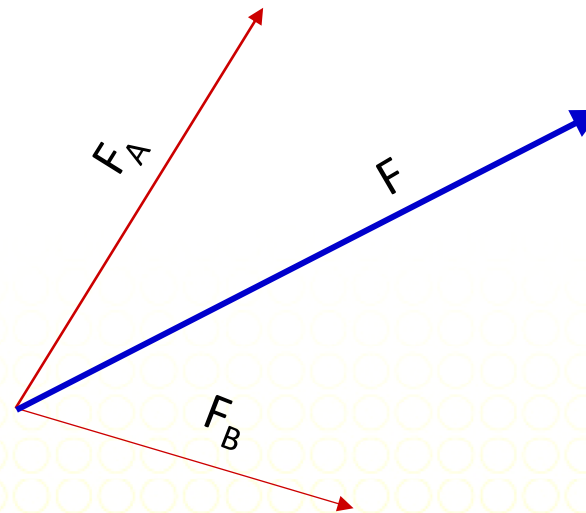


# Resolution of Forces

- A single force can be broken into two separate components.
- The two components can be determined by using the parallelogram law.
- It is the reverse of resultant.



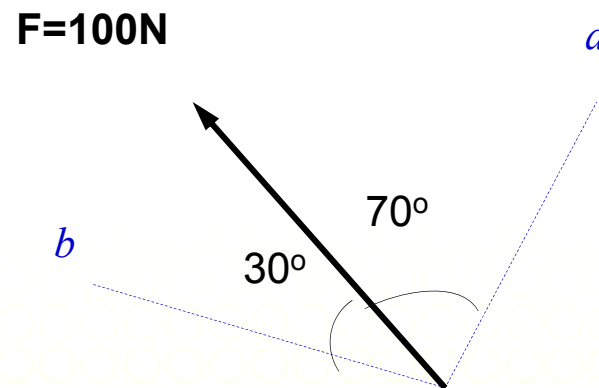
Force  $F$  can be replaced by  $F_A$  and  $F_B$  that produce the same effect



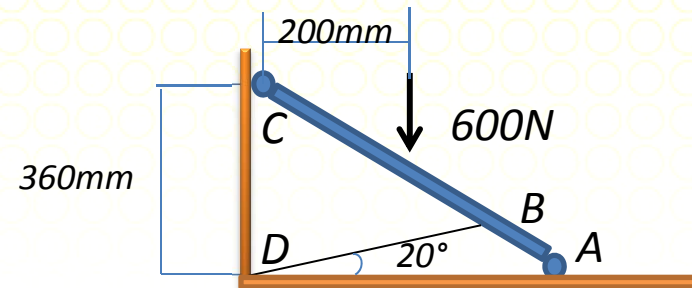
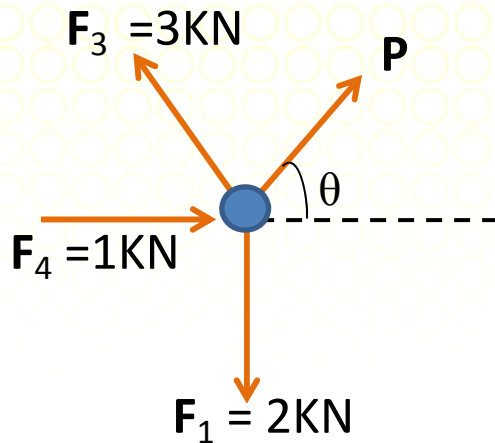
## Example 3

Determine the components of force  $F=100\text{N}$  for the axis system of  $a$  and  $b$  as shown.

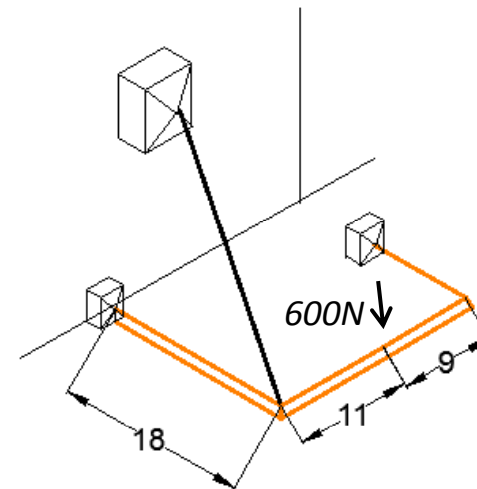
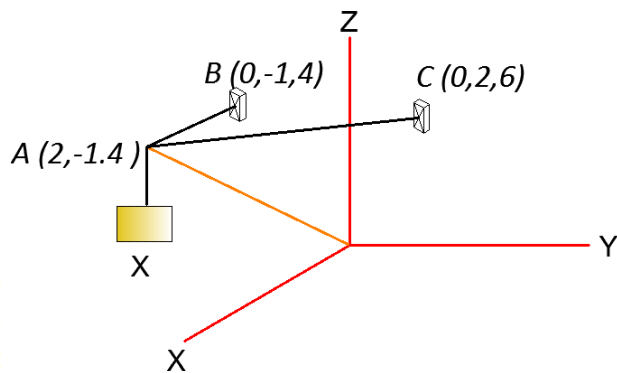
[Answer :  $F_A = 50.8\text{ N}$ ,  $F_B = 95.4\text{ N}$ ]



Scalar notation is used to solve problems for coplanar forces – 2D

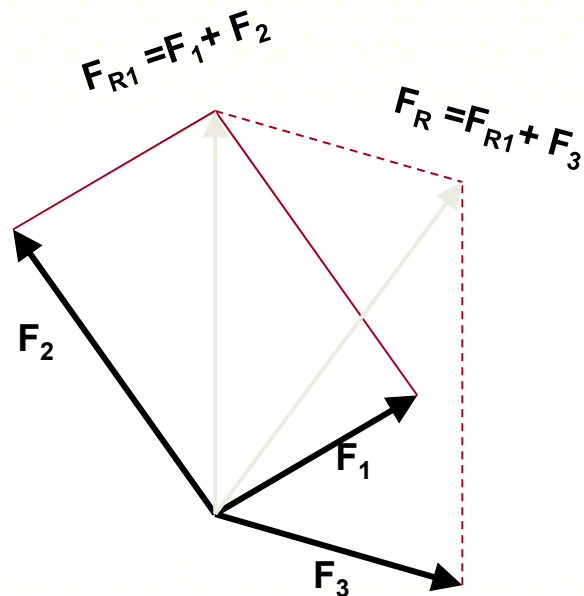


Cartesian vector notation is used in three dimensional problems.



# Resultant of more than 2 Forces

If **more than two** forces are added;



*It requires extensive geometric and trigonometric calculation to determine the magnitude and direction of the resultant.*

An easier way is to use **Rectangular-component method.**



The sense of **direction** is represented graphically by the **arrow head** .

For analytical work, establish a notation for representing the sense of direction of the rectangular components.

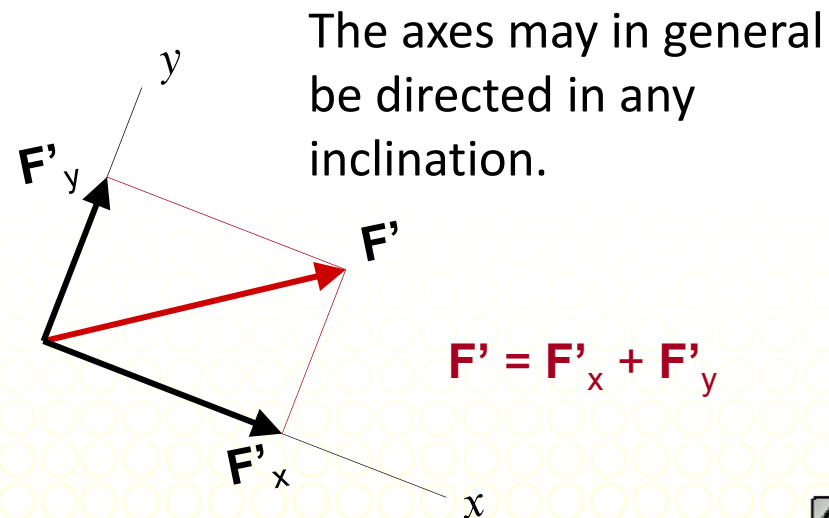
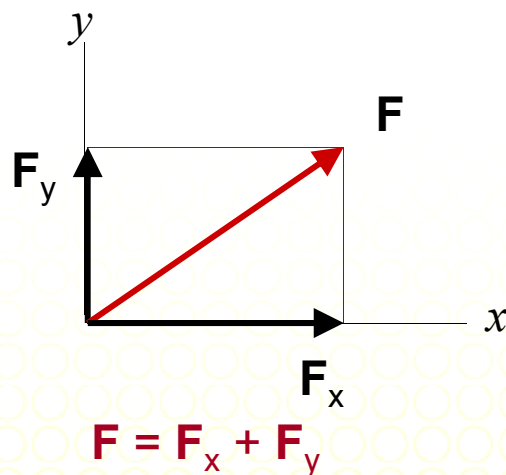
This can be done by either **Scalar Notation** or **Cartesian Vector Notation**.



# Rectangular Components of Coplanar Force

## Method

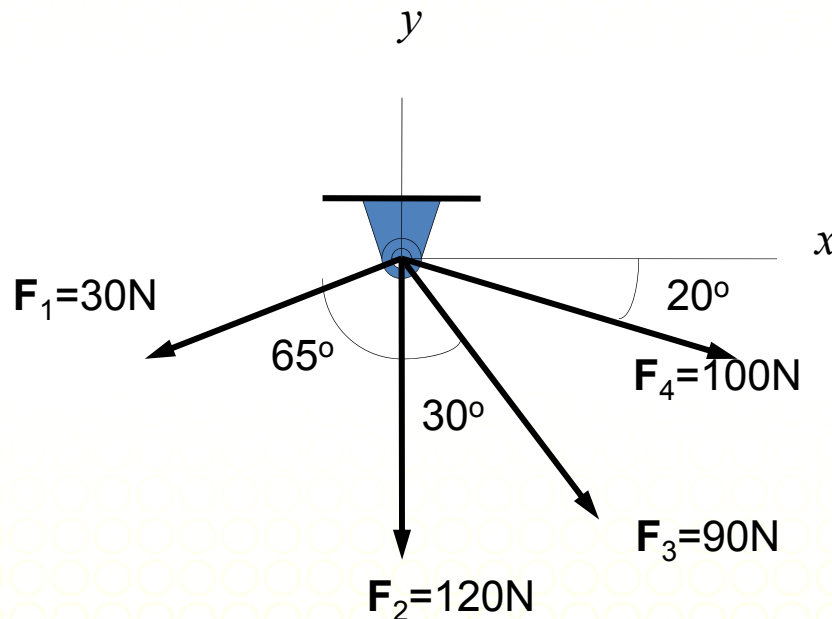
- Sum up the **components** of each force along specified axes algebraically, and then form a resultant.
- Resolved each force into its **rectangular components**  $F_x$  and  $F_y$  which lie along the  $x$  and  $y$  axes.



# Example 4

Four forces act on an eye bolt. Determine the resultant of the forces on the bolt.

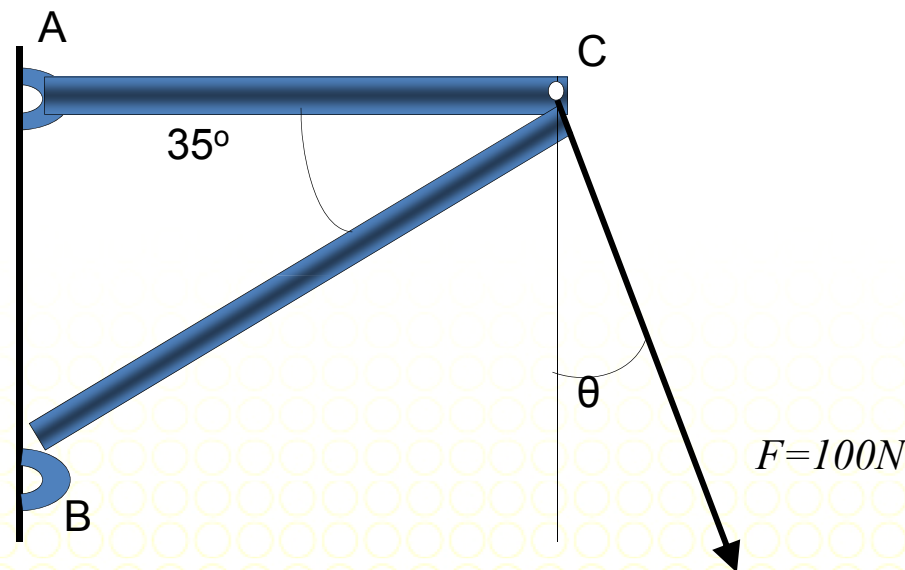
[ANSWER  $F_{Rx} = 111.8\text{N}$ ,  $F_{Ry} = -244.8\text{N}$ ,  $F_R = 269\text{N}$ ,  $\theta = -65.5^\circ$ ]



## Example 5

Resolve the force  $F$  acting at  $C$  into two components acting along members  $AC$  and  $BC$ , if  $\theta = 20^\circ$ . Determine  $\theta$ , so that the component  $F_{AC}$  is directed toward  $C$  and has a magnitude of  $150\text{N}$ .

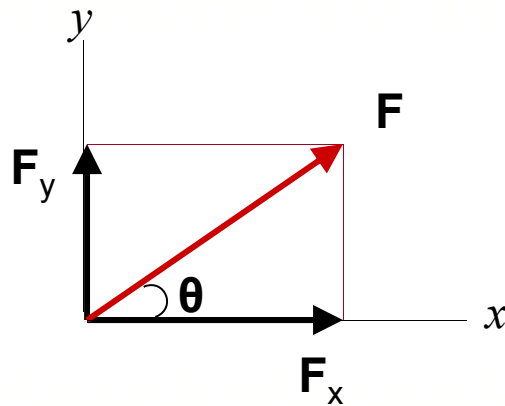
[Answer :  $F_{CB} = 163.8\text{ N}$  ,  $F_{AC} = 168.4\text{ N}$  ,  $\theta = 4.3^\circ$  ]





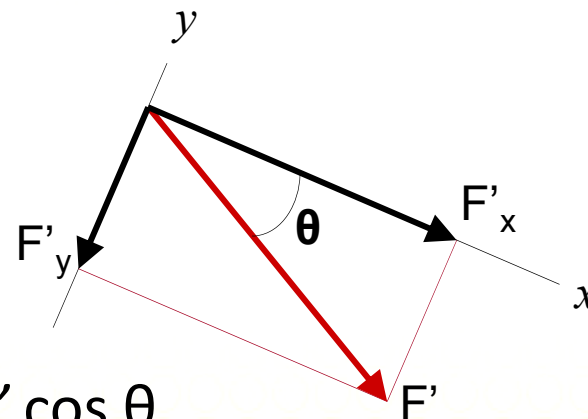
# 1. Scalar Notation

- Since the  $x$  and  $y$  axes have designated +ve and –ve directions, the magnitude and directional sense of the components of a force can be expressed in terms of **algebraic scalars**.
- the component is represented by +ve scalar  $F$  if the sense of direction is along the +ve axis and vice versa.



$$F_x = F \cos \theta$$

$$F_y = F \sin \theta$$

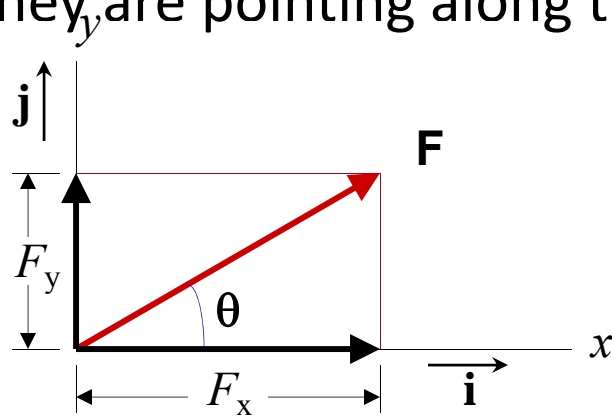


$$F'_x = F' \cos \theta$$

$$F'_y = -F' \sin \theta \text{ (–ve opposite to the direction of +ve y-axis)}$$

## 2. Cartesian Vector Notation

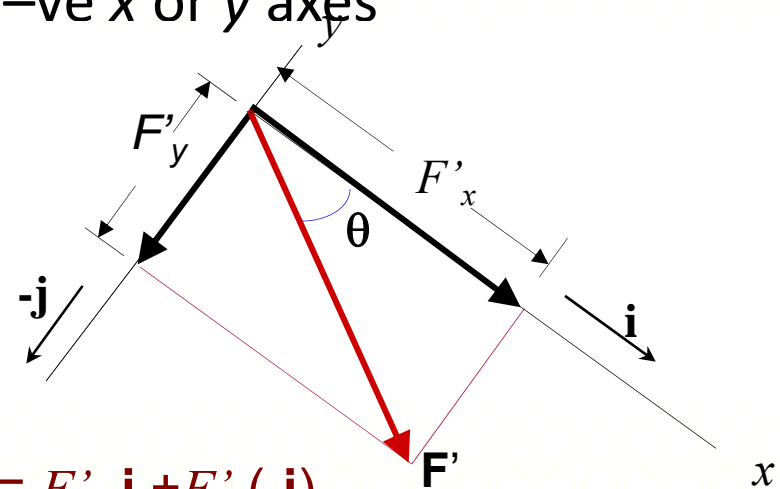
- In 2D, the Cartesian **unit vectors**  $\mathbf{i}$  and  $\mathbf{j}$  are used to show the direction of the  $x$  and  $y$  axes
- The unit vectors have a dimensionless magnitude, and it's described analytically by  $+$  and  $-$  signs, depending whether they are pointing along the  $+ve$  or  $-ve$   $x$  or  $y$  axes



$$\mathbf{F} = F_x \mathbf{i} + F_y \mathbf{j}$$

$$F_x = F \cos \theta$$

$$F_y = F \sin \theta$$



$$\mathbf{F}' = F'_x \mathbf{i} + F'_y (-\mathbf{j})$$

$$\mathbf{F}' = F'_x \mathbf{i} - F'_y \mathbf{j}$$

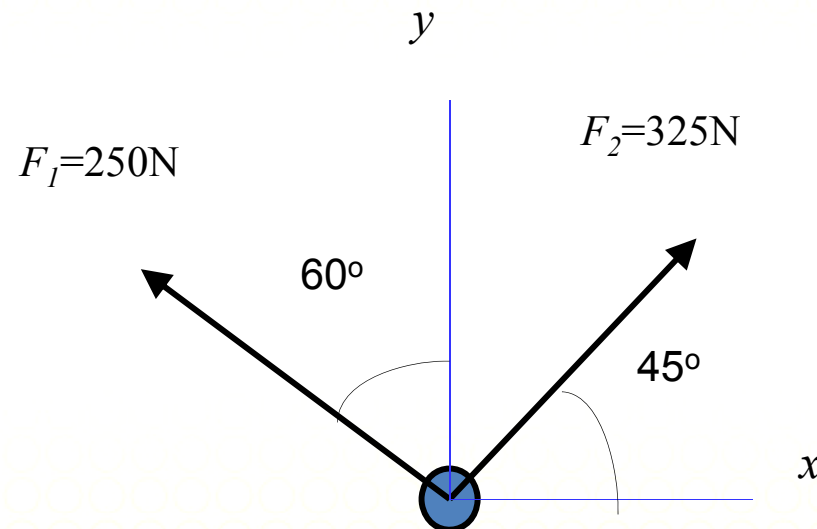
$$F'_x = F' \cos \theta$$

$$F'_y = F' \sin \theta$$



# Example 6

Determine the magnitude and orientation of the resultant force using Cartesian vector method. *[Answer :  $F_R = 13.3 i + 354.8 j$ ]*



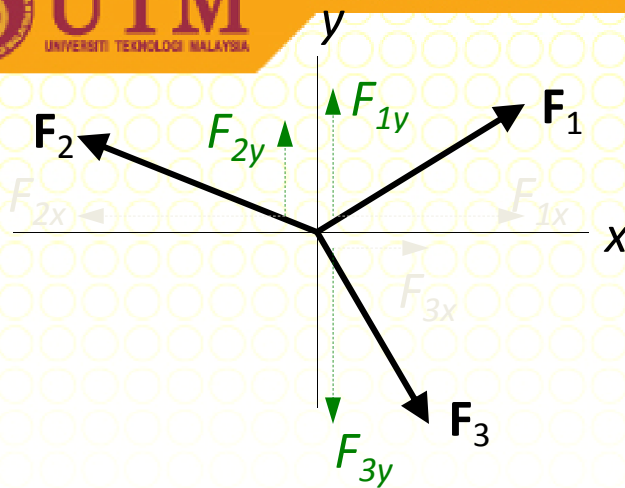
# Coplanar Resultant Force [2D]

## (Rectangular-Component Method)

- Either of the two methods (*Scalar* or *Cartesian vector*) can be used to determine the resultants.
- Each force is resolved into  $x$  and  $y$  components and total up all the components using scalar algebra.
- Apply parallelogram law to obtain resultant force by adding the resultant of the  $x$  and  $y$  components.







## Using Scalar notation

$$(\rightarrow +) \quad F_{Rx} = F_{1x} - F_{2x} + F_{3x}$$

$$(\uparrow +) \quad F_{Ry} = F_{1y} + F_{2y} - F_{3y}$$

Good  
for 2D  
problems

## Using Cartesian vector notation

$$\mathbf{F}_1 = F_{1x} \mathbf{i} + F_{1y} \mathbf{j}$$

$$\mathbf{F}_2 = -F_{2x} \mathbf{i} + F_{2y} \mathbf{j}$$

$$\mathbf{F}_3 = F_{3x} \mathbf{i} - F_{3y} \mathbf{j}$$

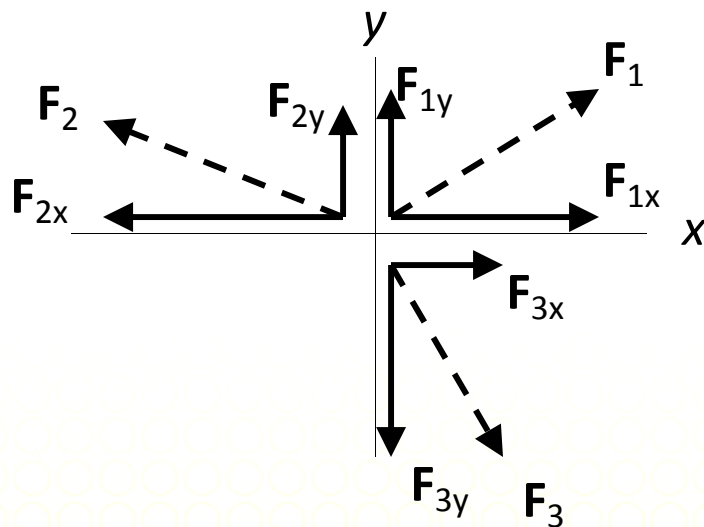
$$\mathbf{F}_R = \mathbf{F}_1 + \mathbf{F}_2 + \mathbf{F}_3$$

$$= F_{1x} \mathbf{i} + F_{1y} \mathbf{j} - F_{2x} \mathbf{i} + F_{2y} \mathbf{j} + F_{3x} \mathbf{i} - F_{3y} \mathbf{j}$$

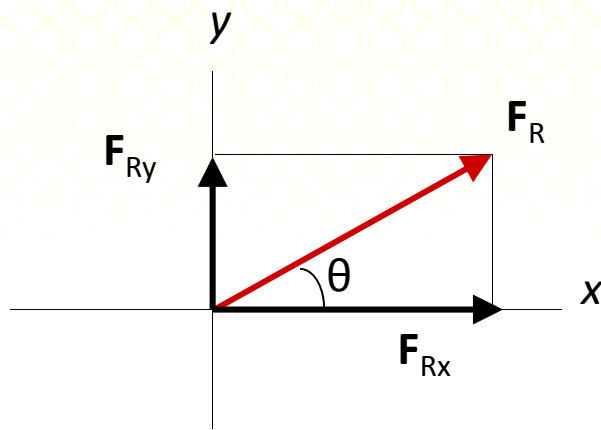
$$= (F_{1x} - F_{2x} + F_{3x}) \mathbf{i} + (F_{1y} + F_{2y} - F_{3y}) \mathbf{j}$$

$$= F_{Rx} \mathbf{i} + F_{Ry} \mathbf{j}$$

Good  
for 3D  
problems



The resultant can be represented by the algebraic sum of the x and y components:



$$F_{RX} = \sum F_x$$

$$F_{RY} = \sum F_y$$

The magnitude  $F_R$  can be found from Pythagoras theorem;

$$F_R = \sqrt{F_{RX}^2 + F_{RY}^2}$$

The direction angle,  $\theta$

$$\theta = \tan^{-1} \frac{F_{RY}}{F_{RX}}$$

## Example 7

Express each of the three forces acting the column in Cartesian vector form and compute the magnitude of the resultant force.

*[Answer :  $F_R = 443.5 \text{ N}$  ,  $\theta = - 84.3^\circ$  ]*

